

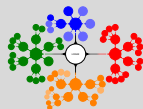
# Lecture 6

## Programming Using the Message-Passing Paradigm III

MPI: the Message Passing Interface; Parallelization Application  
Example - Pi Computation

*IKC-MH.57 Introduction to High Performance and Parallel  
Computing at April 14, 2023*

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## 1 Parallelization Application Example

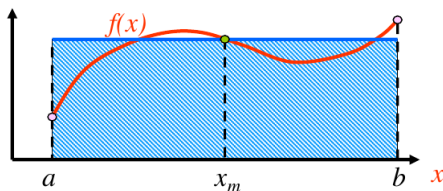
### Pi Computation

## Pi Computation I

- $\pi$  by numerically evaluating the integral

$$\int_0^1 \frac{1}{1+x^2} dx = \frac{\pi}{4}$$

- Midpoint Rule for  $\int_a^b f(x) dx \approx (b-a)f(x_m)$



**Figure:** Midpoint Rule.

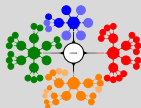
- Midpoint Rule becomes

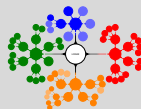
$$\int_0^1 \frac{1}{1+x^2} dx \approx \sum_{i=1}^n \frac{1}{1 + \left(\frac{i-0.5}{n}\right)^2}$$



### Sequential Code:

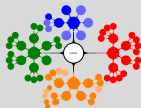
```
#include <stdio.h>
#include <math.h>
int main(int argc, char* argv[])
{
    int done = 0, n, i;
    double PI25DT = 3.141592653589793238462643;
    double mypi, h, sum, x;
    while (!done)
    {
        printf("Enter the number of intervals: (0 quits) ");
        scanf("%d",&n);
        if (n == 0) break; /* Quit when "0" entered*/
        /* Integral limits are from 0 to 1 */
        h = (1.0-0.0)/(double)n; /* Step length*/
        sum = 0.0; /* Initialize sum variable */
        /* loop over interval for integration*/
        for (i = 1; i <= n; i += 1)
        {
            x = h * ((double)i - 0.5); /* Middle point at step */
            sum += 4.0 / (1.0 + x*x); /* Sum up at each step */
            //("i=%d x=%f sum=%f \n",i,x,sum); /* print intermediate steps */
        }
        mypi = h * sum; /* Obtain resulting pi number */
        printf("pi is approximately %.16f, Error is %.16f\n",mypi, \\
            fabs(mypi - PI25DT));
    }
}
```





```
mpicc -o sequential_pi sequential_pi.c
./sequential_pi
Enter the number of intervals: (0 quits) 100
pi is approximately 3.1416009869231254, Error is 0.0000083333333323
Enter the number of intervals: (0 quits) 1000
pi is approximately 3.1415927369231227, Error is 0.0000008333333296
Enter the number of intervals: (0 quits) 10000
pi is approximately 3.1415926544231341, Error is 0.0000000083333410
Enter the number of intervals: (0 quits) 0
```

**Figure:** Sequential Code Output.



- Parallel Code:
  - The master process reads number of intervals from standard input, this number is then sent to the processes.
  - Having received the number of intervals, each process evaluates the total area of **n/size** rectangles under the curve.
  - The contributions to the total area under the curve are collected from participating processes by the master process, which then adds them up, and prints the result on standard output.

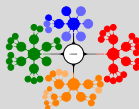
# Pi Computation V

```
#include <stdio.h>
#include <math.h>
#include "mpi.h"

int main(int argc, char* argv[])
{
    int done = 0, n, i;
    double PI25DT = 3.141592653589793238462643;
    double mypi, h, sum, x;
    int size, rank, me;
    int tag=11;
    MPI_Status status;
    double mysum;
    double pi;

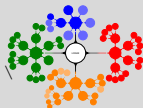
    MPI_Init(&argc, &argv); /* Initialize MPI */
    MPI_Comm_size(MPI_COMM_WORLD, &size); /* Get number of processes */
    MPI_Comm_rank(MPI_COMM_WORLD, &rank); /* Get own identifier */

    while (!done)
    {
        if (rank == 0) { /* Process 0 does this */
            printf("Enter the number of intervals: (0 quits) ");
            scanf("%d", &n);
            /* Send a message containing number of intervals to all \
                other processes */
            for (i=1; i<size; i++) {
                MPI_Send(&n, 1, MPI_INT, i, tag, MPI_COMM_WORLD); \
                    /* Blocking send */
            }
        }
    }
}
```



## Pi Computation VI

```
if (n == 0) break; /* Quit when "0" entered */
/* Computing local pi number for rank 0 process*/
/* Integral limits are from 0 to 1 */
h = (1.0-0.0)/(double)n; /* Step length*/
mysum = 0.0; /* Initialize sum variable */
for (i = rank+1; i <= n; i += size) /* Loop over interval
                                     for integration */
{
    x = h * ((double)i - 0.5); /* Middle point at step */
    mysum += 4.0 / (1.0 + x*x); /* Sum up at each step */
//printf("i=%d x=%f sum=%f \n",i,x,sum); /* Intermediate steps */
}
mypi = h * mysum; /* Obtain local resulting pi number */
/* Receive a message containing local resulting pi number \
   from all other processes */
for (i=1; i<size; i++) {
    MPI_Recv (&pi, 1, MPI_DOUBLE, i, tag, MPI_COMM_WORLD, \
              &status); /* Blocking receive */
    printf("Process 0 : Received local resulting pi \
           number: %.16f from process %d \n",pi,i);
    mypi=mypi+pi; /* Reduce all local values to mypi \
                  variable */
}
printf("pi is approximately %.16f, Error is %.16f\n",mypi, \
       fabs(mypi - PI25DT));
}
else /* Other processes do this */
{
    MPI_Recv (&n, 1, MPI_INT, 0, tag, MPI_COMM_WORLD, \
              &status); /* Blocking receive */
```







```
printf("Process %d : Received number of intervals as %d \
      from process 0 \n",rank, n);
if (n == 0) break; /* Quit when "0" entered*/
/* Computing local pi number for other processes*/
/* Integral limits are from 0 to 1 */
h = (1.0-0.0)/(double)n; /* Step length*/
mysum = 0.0; /* Initialize sum variable */
for (i = rank+1; i <= n; i += size) /* Loop over interval
      for integration */
{
    x = h * ((double)i - 0.5); /* Middle point at step */
    mysum += 4.0 / (1.0 + x*x); /* Sum up at each step */
//printf("i=%d x=%f sum=%f \n",i,x,sum); /* Intermediate steps */
}
mypi = h * mysum; /* Obtain local resulting pi number */
/* Send a message containing local resulting pi number
      to master processes */
MPI_Send(&mypi, 1, MPI_DOUBLE, 0, tag, MPI_COMM_WORLD);
      /* Blocking send */
}
}
MPI_Finalize();
}
```



```
mpicc -o parallel_pi parallel_pi.c
Enter the number of intervals: (0 quits) 100
Process 1 : Received number of intervals as 100 from process 0
Process 2 : Received number of intervals as 100 from process 0
Process 3 : Received number of intervals as 100 from process 0
Process 0 : Received local resulting pi
Process 0 : Received local resulting pi
Process 0 : Received local resulting pi
pi is approximately 3.1416009869231249, Error is 0.000008333333318
Enter the number of intervals: (0 quits) 1000
Process 2 : Received number of intervals as 1000 from process 0
Process 3 : Received number of intervals as 1000 from process 0
Process 1 : Received number of intervals as 1000 from process 0
Process 0 : Received local resulting pi
Process 0 : Received local resulting pi
Process 0 : Received local resulting pi
pi is approximately 3.1415927369231262, Error is 0.000000833333331
Enter the number of intervals: (0 quits) 10000
Process 1 : Received number of intervals as 10000 from process 0
Process 2 : Received number of intervals as 10000 from process 0
Process 3 : Received number of intervals as 10000 from process 0
Process 0 : Received local resulting pi
Process 0 : Received local resulting pi
Process 0 : Received local resulting pi
pi is approximately 3.1415926544231239, Error is 0.000000083333307
Enter the number of intervals: (0 quits) 0
Process 1 : Received number of intervals as 0 from process 0
Process 2 : Received number of intervals as 0 from process 0
Process 3 : Received number of intervals as 0 from process 0

number: 0.7879260283629755 from process 1
number: 0.7829244650957667 from process 2
number: 0.7778741525634219 from process 3

number: 0.7856484350120356 from process 1
number: 0.7851484334495280 from process 2
number: 0.7846479331370270 from process 3

number: 0.7854231661065627 from process 1
number: 0.7853731661050003 from process 2
number: 0.7853231611046871 from process 3
```

**Figure:** Parallel Code Output.