

1 MPI Hands-On; Collective Communications I

1. **Broadcasting an integer value to all of the MPI processes,** A program `code10.c` that reads an integer value from the terminal and distributes the value to all of the MPI processes.

- Each process should print out its rank and the value it received. Values should be read until a negative integer is given as input.
- You may find it helpful to include a `fflush(stdout)` to the code; after the `printf` calls in your program. Without this, output may not appear when you expect it.

```
1 #include <stdio.h>
2 #include "mpi.h"
3
4 int main( int argc, char **argv )
5 {
6     int rank, value;
7     MPI_Init( &argc, &argv );
8
9     MPI_Comm_rank( MPI_COMM_WORLD, &rank );
10    do {
11        if (rank == 0)
12            scanf( "%d", &value );
13
14        MPI_Bcast( &value, 1, MPI_INT, 0, MPI_COMM_WORLD );
15
16        printf( "Process %d got %d\n", rank, value );
17        fflush( stdout );
18    } while (value >= 0);
19
20    MPI_Finalize( );
21    return 0;
22 }
```

2. **Broadcasting the name of the master process**, A program [code11.c](#) that first broadcasts the name of the master process then each nodes send hello messages to master node.

```

1 #include <stdio.h>
2 #include <string.h>
3 #include <mpi.h>
4
5 #define TRUE 1
6 #define FALSE 0
7 #define MASTER_RANK 0
8
9 int main( int argc , char *argv[] )
10 {
11     int count , pool_size , my_rank , my_name_length , i_am_the_master =
12         FALSE;
13     char my_name[BUFSIZ/2] , master_name[BUFSIZ/2] , send_buffer[2*BUFSIZ
14         ] ,
15         recv_buffer[2*BUFSIZ];
16     MPI_Status status;
17
18     MPI_Init(&argc , &argv );
19     MPI_Comm_size(MPILCOMM_WORLD, &pool_size);
20     MPI_Comm_rank(MPILCOMM_WORLD, &my_rank);
21     MPI_Get_processor_name(my_name , &my_name_length );
22
23     if ( my_rank == MASTER_RANK ) {
24         i_am_the_master = TRUE;
25         strcpy ( master_name , my_name );
26     }
27
28     MPI_Bcast( master_name , BUFSIZ, MPILCHAR, MASTER_RANK, MPILCOMM_WORLD
29         );
30
31     sprintf(send_buffer , "hello %s , greetings from %s , rank = %d",
32             master_name , my_name , my_rank );
33     MPI_Send ( send_buffer , strlen(send_buffer) + 1, MPILCHAR,
34             MASTER_RANK, 0 , MPILCOMM_WORLD );
35
36     if ( i_am_the_master ) {
37         for ( count = 1; count <= pool_size; count++ ) {
38             MPI_Recv ( recv_buffer , BUFSIZ, MPILCHAR, MPLANY_SOURCE,
39             MPLANY_TAG,
40             MPILCOMM_WORLD, &status );
41             printf ("%s\n" , recv_buffer );
42         }
43     }
44     MPI_Finalize();
45 }
```

3. Computation of PI number with collective communications.

This example `code12.c` evaluates π by numerically evaluating the integral

$$\int_0^1 \frac{1}{1+x^2} dx = \frac{\pi}{4}$$

This code computes PI (with a very simple method) but does not use **MPI_Send** and **MPI_Recv**. Instead, it uses *collective* operations to send data to and from all of the running processes.

- The routine **MPI_Bcast** sends data from one process to all others.
- The routine **MPI_Reduce** combines data from all processes (by adding them in this case), and returning the result to a single process.

```

1 #include <stdio.h>
2 #include "mpi.h"
3 #include <math.h>
4
5 int main( int argc , char *argv [] )
6 {
7     int done = 0, n, myid, numprocs, i, rc;
8     double PI25DT = 3.141592653589793238462643;
9     double mypi, pi, h, sum, x, a;
10
11    MPI_Init(&argc,&argv);
12    MPI_Comm_size(MPILCOMM_WORLD,&numprocs);
13    MPI_Comm_rank(MPILCOMM_WORLD,&myid);
14    while (!done)
15    {
16        if (myid == 0) {
17            printf("Enter the number of intervals: (0 quits) ");
18            scanf("%d",&n);
19        }
20        MPI_Bcast(&n, 1, MPI_INT, 0, MPILCOMM_WORLD);
21        if (n == 0) break;
22
23        h = 1.0 / (double) n;
24        sum = 0.0;
25        for (i = myid + 1; i <= n; i += numprocs) {
26            x = h * ((double)i - 0.5);
27            sum += 4.0 / (1.0 + x*x);
28        }
29        mypi = h * sum;
30
31        MPI_Reduce(&mypi, &pi, 1, MPI_DOUBLE, MPI_SUM, 0, MPILCOMM_WORLD);
32
33        if (myid == 0)
34            printf("pi is approximately %.16f, Error is %.16f\n",
35                   pi, fabs(pi - PI25DT));
36    }
37    MPI_Finalize();
38 }
```