



Lecture 12

Numerical Differentiation and Integration

Numerical Integration-The Trapezoidal Rule

Ceng375 *Numerical Computations* at January 06, 2011

Numerical
Differentiation and
Integration with a
Computer

Differentiation with a
Computer

Numerical Integration - The
Trapezoidal Rule

The Trapezoidal Rule

The Composite
Trapezoidal Rule

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1 Numerical Differentiation and Integration with a Computer

Differentiation with a Computer

Numerical Integration - The Trapezoidal Rule

The Trapezoidal Rule

The Composite Trapezoidal Rule

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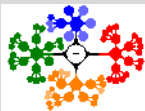
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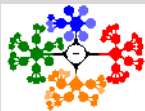
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 - Employs the interpolating polynomials to derive formulas for getting derivatives.
 - These can be applied to functions known explicitly as well as those whose values are found in a table.
- **Numerical Integration-The Trapezoidal Rule:**
 - **Approximates, the integrand function with a linear interpolating polynomial to derive a very simple but important formula for numerically integrating functions between given limits.**

Numerical Differentiation and Integration II

- We continue to exploit the useful properties of polynomials to develop methods for a computer to do **integrations** and to find **derivatives**.



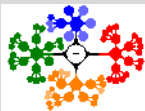
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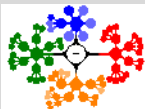
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- But doing so in getting derivatives requires the subtraction of quantities that are nearly equal and that runs into **round-off** error.
- However, integration involves only addition, so round-off is not problem.
- We cannot often find the true answer numerically because the analytical value is the limit of the sum of an infinite number of terms.
- We must be satisfied with approximations for both derivatives and integrals but, for most applications, the **numerical answer is adequate**.

- The derivative of a function, $f(x)$ at $x = a$, is defined as

$$\left. \frac{df}{dx} \right|_{x=a} = \lim_{\Delta x \rightarrow 0} \frac{f(a + \Delta x) - f(a)}{\Delta x}$$



Differentiation with a Computer I

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$$\left. \frac{df}{dx} \right|_{x=a} = \frac{f(a + \Delta x) - f(a)}{\Delta x}$$

- Recalculating with smaller and smaller values of x starting from an initial value.
- What happens if the value is not small enough?

- We should expect to find an *optimal value* for x .



Differentiation with a Computer II

- We should expect to find an ***optimal value*** for x .
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- Starting with $\Delta x = 0.05$ and halving Δx each time. Table 1 gives the results.
- We find that the errors of the approximation decrease as Δx is reduced until about $\Delta x = 0.05/128$.



Δx	Approximation	Error	Ratio of errors
0.05	4.05010	-0.11528	
0.05/2	4.10955	-0.05583	2.06
0.05/4	4.13795	-0.02743	2.04
0.05/8	4.15176	-0.01362	2.01
0.05/16	4.15863	-0.00675	2.02
0.05/32	4.16199	-0.00389	1.99
0.05/64	4.16382	-0.00156	2.18
0.05/128	4.16504	-0.00034	4.67*
0.05/256	4.16504	-0.00034	
0.05/512	4.16504	-0.00034	
0.05/1024	4.16992	0.00454	
0.05/2048	4.17969	0.01430	

Table: Forward-difference approximations for $f(x) = e^x \sin(x)$.

Differentiation with a Computer IV

- Notice that each successive error is about 1/2 of the previous error as Δx is halved until Δx gets quite small, **at which time round off affects the ratio.**



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- At values for Δx smaller than $0.05/128$, the error of the approximation increases due to round off.





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- At values for Δx smaller than $0.05/128$, the error of the approximation increases due to round off.
- In effect, the best value for Δx is **when the effects of round-off and truncation errors are balanced.**

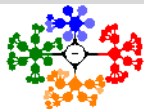


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- **If a backward-difference approximation is used; similar results are obtained.**



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- **Backward-difference** approximation.

$$\left. \frac{df}{dx} \right|_{x=a} = \frac{f(a) - f(a - \Delta x)}{\Delta x}$$

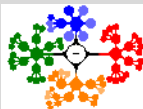


With MATLAB. **Analytical answer** to the function of Table 1.

```
format long;  
syms x;  
f='exp(x)*sin(x)';  
df=diff(f,x)  
exactvalue=subs(df,1.9,'x')
```

Differentiation with a Computer VI

With MATLAB. **Numerical answer** to the function of Table 1.



```
%%%Forward-Difference%%  
disp('Step      Del      Numerical      Error      Error')  
disp('      Derivative      Ratio')  
disp('-----')  
x=1.9;  
delini=1;  
error(1)=1;  
for i=1:30  
    del=delini/2;  
    xplus=x+del;  
    f=exp(x).*sin(x);  
    fplus=exp(xplus).*sin(xplus);  
    num=fplus-f;  
    deriv=num/del;  
    error(i+1)=deriv-exactvalue;  
    [D]=sprintf('%2d %1.15f %12.10f %12.10f %f ', i, del, deriv, error(i),  
                error(i)/error(i+1));  
    disp(D);  
    delini=del;  
end
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Differentiation with a Computer VII

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Differentiation with a Computer VII

- It is not by chance that the errors are about **halved each time**.
- Look at this Taylor series where we have used h for Δx :

$$f(x + h) = f(x) + f'(x) * h + f''(\xi) * h^2 / 2$$



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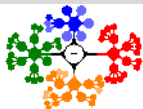
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- If we repeat this but begin with the Taylor series for $f(x - h)$, it turns out that

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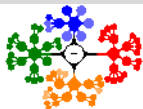
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- Where ζ is between x and $x - h$.



Differentiation with a Computer VIII

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Differentiation with a Computer VIII



- The two error terms of Eqs. 1 and 2 are not identical though both are $O(h)$.
- If we add Eqs. 1 and 2, then divide by 2, we get the **central-difference** approximation to the derivative:

$$f'(x) = \frac{f(x+h) - f(x-h)}{2h} - f'''(\xi) * \frac{h^2}{6} \quad (3)$$

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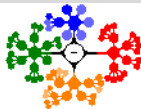


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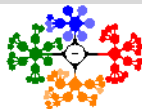
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- This shows that using a central-difference approximation is a much preferred way to estimate the derivative.
- Even though we use the same number of computations of the function at each step,
- **we approach the answer much more rapidly.**

Differentiation with a Computer IX

With MATLAB,

```
%%%Central-Difference%%%  
disp('Step      Del      Numerical      Error      Error')  
disp('      Derivative      Ratio')  
disp('-----')  
x=1.9;  
delini=0.1;  
error(1)=1;  
for i=1:20  
    del=delini/2;  
    xplus=x+del;  
    xminus=x-del;  
    fplus=exp(xplus).*sin(xplus);  
    fminus=exp(xminus).*sin(xminus);  
    num=fplus-fminus;  
    deriv=num/(2*del);  
    error(i+1)=deriv-exactvalue;  
    [D]=sprintf('%2d %1.15f %12.10f %12.10f %f ',i,del,deriv,error(i),  
                error(i)/error(i+1));  
    disp(D);  
    delini=del;  
end
```



Differentiation with a Computer X



Table 2 illustrates this, showing that errors decrease about four fold when Δx is halved (as Eq. 3 predicts) and that a more accurate value is obtained.

Δx	Approximation	Error	Ratio of errors
0.05	4.15831	-0.00708	
0.05/2	4.16361	-0.00177	4.00
0.05/4	4.16496	-0.00042	4.21
0.05/8	4.16527	-0.00011	3.80
0.05/16	4.16534	-0.00004	2.75
0.05/32	4.16534	-0.00004	
0.05/64	4.16565	-0.00027	

Table: Central-difference approximations for $f(x) = e^x \sin(x)$.

Numerical Integration - The Trapezoidal Rule I

- Given the function, $f(x)$, the **antiderivative** is a function $F(x)$ such that $F'(x) = f(x)$.



Numerical Integration - The Trapezoidal Rule I

- Given the function, $f(x)$, the **antiderivative** is a function $F(x)$ such that $F'(x) = f(x)$.
- The definite integral

$$\int_a^b f(x) dx = F(b) - F(a)$$

can be evaluated from the antiderivative.



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- Given the function, $f(x)$, the **antiderivative** is a function $F(x)$ such that $F'(x) = f(x)$.
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can be evaluated from the antiderivative.

- **Still, there are functions that do not have an antiderivative expressible in terms of ordinary functions.**

```
>> syms x
>> int(exp(x)/log(x))
Warning: Explicit integral could not be found.
> In sym.int at 58
ans = int(exp(x)/log(x), x)
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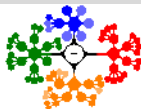
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- Is there any way that the definite integral can be found when the antiderivative is unknown?





- We can do it numerically by using the **composite trapezoidal rule**

```
>> fx(i)=exp(x(i))/log(x(i))
>> x=linspace(2,3,10);
>> for i=1:10
fx(i)=exp(x(i))/log(x(i));
end
>> result=fx(1)+fx(10);
>> for i=2:9
result=result+2*fx(i);
end
>> result=((3-2)/(10-1))/2)*result
%%%result=(0.1111/2)*result
result =    13.6904
```

Numerical Integration - The Trapezoidal Rule III



- The definite integral is the area between the curve of $f(x)$ and the x -axis.

Numerical Integration - The Trapezoidal Rule III



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- That is the principle behind all numerical integration;

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- We divide the distance from $x = a$ to $x = b$ into **vertical strips** and add the areas of these strips.

Numerical Integration - The Trapezoidal Rule III



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- That is the principle behind all numerical integration;
- We divide the distance from $x = a$ to $x = b$ into **vertical strips** and add the areas of these strips.
- The strips are often made equal in widths but that is not always required.

The Trapezoidal Rule I

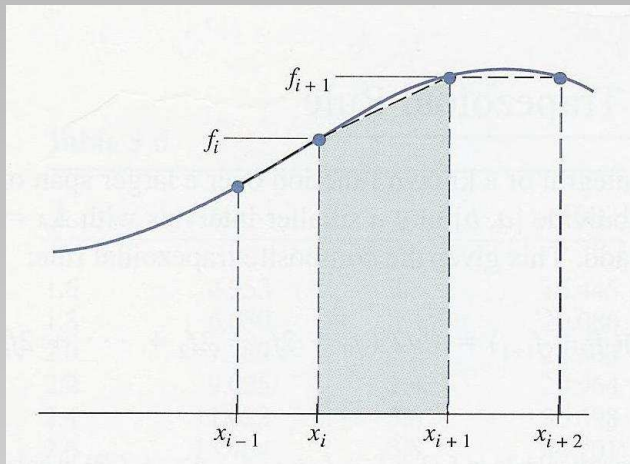


Figure: The trapezoidal rule.

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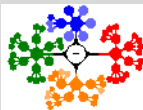
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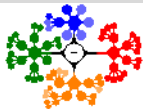


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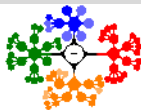
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- What happens, if we are getting the integral of a known function over a larger span of x -values, say, from $x = a$ to $x = b$?



The Composite Trapezoidal Rule I

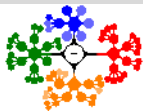
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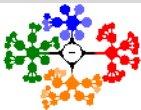
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- If $f''(x)$ is continuous in $[a, b]$, there is some point within $[a,b]$ at which the sum of the $f''(\xi_i)$ is equal to $nf''(\xi)$, where ξ in $[a, b]$.
- We then see that, because $nh = (b - a)$,

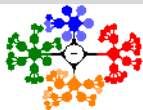
$$\text{Global error} = (-1/12)h^3 nf''(\xi) = \frac{-(b-a)}{12} h^2 f''(\xi) = O(h^2)$$

The Composite Trapezoidal Rule II

- **Example:** Given the values for x and $f(x)$ in Table3.

x	$f(x)$	x	$f(x)$
1.6	4.953	2.8	16.445
1.8	6.050	3.0	20.086
2.0	7.389	3.2	24.533
2.2	9.025	3.4	29.964
2.4	11.023	3.6	36.598
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- Use the trapezoidal rule to estimate the integral from $x = 1.8$ to $x = 3.4$.



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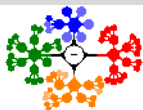
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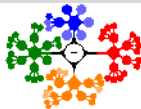
- Use the trapezoidal rule to estimate the integral from $x = 1.8$ to $x = 3.4$.
- **Applying the trapezoidal rule:**

$$\int_{1.8}^{3.4} f(x) dx \approx \frac{0.2}{2} [6.050 + 2(7.389) + 2(9.025) + 2(11.023) + 2(13.464) + 2(16.445) + 2(20.086) + 2(24.533) + 29.964] = 23.9944$$



The Composite Trapezoidal Rule III

- The data in Table 3 are for $f(x) = e^x$ and the true value is $e^{3.4} - e^{1.8} = 23.9144$.



$$\begin{aligned} \text{Error} &= -\frac{1}{12}h^3nf''(\xi), \quad 1.8 \leq \xi \leq 3.4 \\ &= -\frac{1}{12}(0.2)^3(8) * \left\{ \begin{array}{l} e^{1.8} \quad (max) \\ e^{3.4} \quad (min) \end{array} \right\} = \left\{ \begin{array}{l} -0.0323 \quad (max) \\ -0.1598 \quad (min) \end{array} \right\} \end{aligned}$$

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- The data in Table 3 are for $f(x) = e^x$ and the true value is $e^{3.4} - e^{1.8} = 23.9144$.
- The trapezoidal rule value is off by 0.08; there are *three digits of accuracy*.

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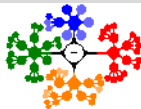
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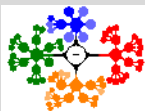
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- The actual error was -0.080 . It is reasonable since the value is in the error bounds.



Thanks for attending and listening.

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Numerical Integration - The
Trapezoidal Rule

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The Composite
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